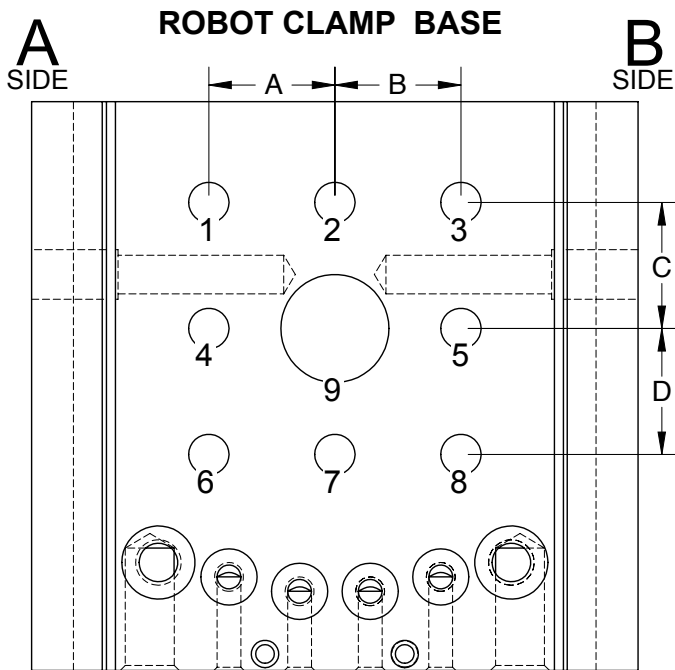


QCS ROBOT TOOLING SYSTEM

WORK SHEET FOR CUSTOM MOUNTING DETAILS:



TAP _____ THREAD @ POSITIONS

1 2 3 4
 5 6 7 8
 9

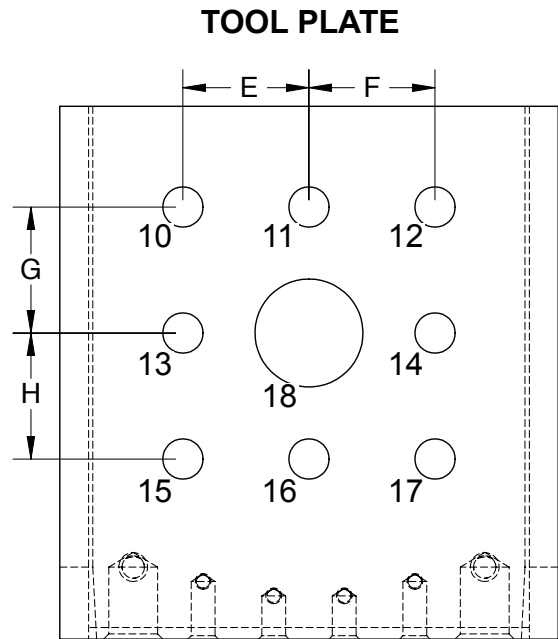
DRILL _____ THRU @ POSITIONS

1 2 3 4
 5 6 7 8
 9

DIMENSIONS: A B

C D

HANDLE SIDE: A B



TAP _____ THREAD @ POSITIONS

10 11 12 13
 14 15 16 17
 18

DRILL _____ THRU @ POSITIONS

10 11 12 13
 14 15 16 17
 18

DIMENSIONS: E F

G H